

### **MLFB-Ordering data**

6SL3210-1KE21-3AF1



Client order no.: Order no. : Offer no. : Remarks :

Item no.: Consignment no. : Project:

Rated da	ıta	General tec	General tech. specifications		
Input		Power factor λ	0.70 0.85		
Number of phases	3 AC	Offset factor cos φ	0.95		
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.97		
Line frequency	47 63 Hz	Sound pressure level (1m)	63 dB		
Rated current (LO)	16.50 A	Power loss	0.18 kW		
Rated current (HO)	12.80 A	A			
Output		Ambier	t conditions		
Number of phases	3 AC	Cooling	Air cooling using an integrated fan		
Rated voltage	400 V		0.009 m³/s (0.318 ft³/s)		
Rated power IEC 400V (LO)	5.50 kW	Cooling air requirement			
Rated power NEC 480V (LO)	7.50 hp	Installation altitude	1000 m (3280.84 ft)		
Rated power IEC 400V (HO)	4.00 kW	Ambient temperature			
Rated power NEC 480V (HO)	5.00 hp	Operation	-10 40 °C (14 104 °F)		
Rated current (IN)	13.00 A	Transport	-40 70 °C (-40 158 °F)		
Rated current (LO)	12.50 A	Storage	-40 70 °C (-40 158 °F)		
Rated current (HO)	8.80 A	Relative humidity			
Max. output current	17.60 A	Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible		
Pulse frequency	4.000 kHz				
Output frequency for vector control	0 240 Hz	Closed-loop control techniques			
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parameterizable Yes			
		V/f with flux current control (FC	CC) Yes		
		V/f ECO linear / square-law	Yes		
Overload capability		Sensorless vector control	Yes		
Low Overload (LO)		Vector control, with sensor	No		

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

#### High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Com	mun	ication	

PROFINET / EtherNet/IP Communication

**Encoderless torque control** 

Torque control, with encoder

No

No



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Mechanical data		Со	Connections		
Degree of protection	IP20 / UL open type	Signal cable			
Size	FSB	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Net weight	2.30 kg (5.07 lb)	Line side			
Width	100 mm (3.94 in)	Version	Plug-in screw terminals		
Height	196 mm (7.72 in)	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)		
Depth	225 mm (8.86 in)	Motor end			
Inputs / outputs		Version	Plug-in screw terminals		
Standard digital inputs		Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)		
Number	6	DC link (for braking resistor)			
Switching level: 0→1	11 V	Version	Plug-in screw terminals		
Switching level: 1→0	5 V	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)		
Max. inrush current	15 mA	Line length, max.	15 m (49.21 ft)		
Fail-safe digital inputs		PE connection	On housing with M4 screw		
Number	1	Max. motor cable length	, and the second		
Digital outputs		Shielded	150 m (492.13 ft)		
Number as relay changeover contact	1	Unshielded	150 m (492.13 ft)		
Output (resistive load)	DC 30 V, 0.5 A	Standards			
Number as transistor	1	Compliance with standards	UL, cUL, CE, C-Tick (RCM)		
Output (resistive load)	DC 30 V, 0.5 A		EMCD: 11 2004/400/EC 1 11 11		
Analog / digital inputs		CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC		
Number	1 (Differential input)				
Analog outputs					

# PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 

1 (Non-isolated output)



## **MLFB-Ordering data**

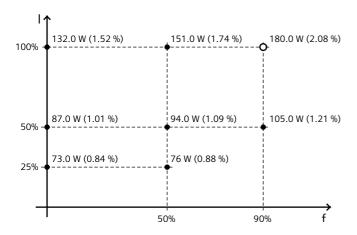
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Figure similar

### Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% /	-65.39 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values